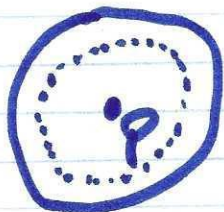
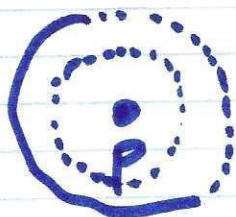


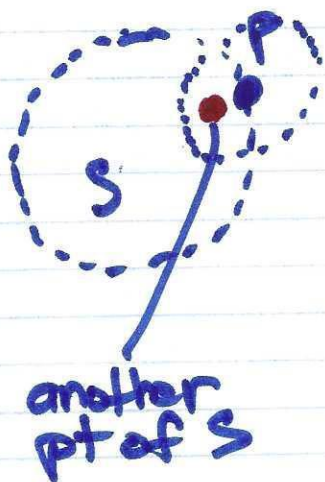
point in an open nbhd



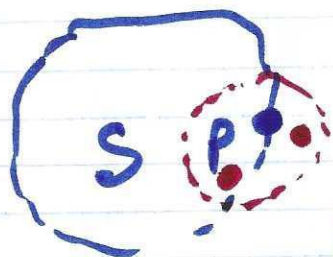
point in closed nbhd



point in arbitrary nbhd



p is a limit point of S
because all open sets containing
 p (i.e. open nbhds) intersect S
in a point other than p



p is a boundary point of S
if every nbhd of p intersects
both S and S^c

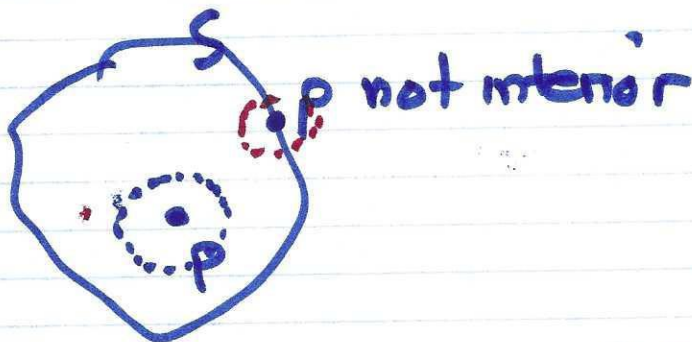
(2)

limit point of S

accumulation pt.
cluster pt
derived pt

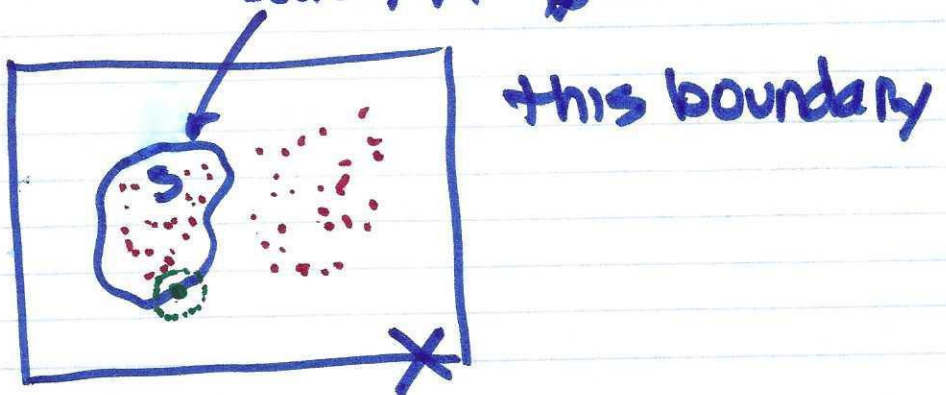
set of all limit points (derived pts) is called the derived set of S , denoted S'
 $\text{cl } S = \text{closure of } S = S \cup S'$

interior point of S is a point contained in an open set itself contained in S



$$\text{int } S = \{ \text{interior pts of } S \}$$

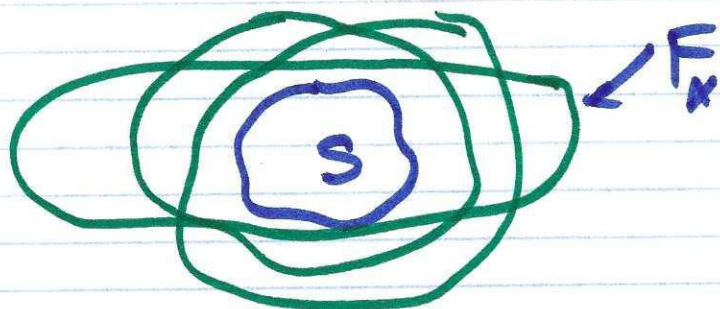
$$\text{ext } S = \text{int } S^c \quad \text{boundary } X - \text{int } S - \text{ext } S$$



F fermé (3)

$$\text{int } S = \bigcup O_\alpha \text{ where } O_\alpha \subset S$$

$$\text{cl } S = \bigcap F_\alpha \text{ where } F_\alpha \supset S : F \text{ closed}$$



closure point (belongs to $\text{cl } S$)

adherent point (adherence)

A topological space is a pair (X, τ)

where X is any ($\neq \emptyset$) set and

$\tau \subset \mathcal{P}^X$. τ is the topology

(i) $\tau = \{ O_\alpha \}_{\alpha \in \Lambda}$ O_α are called open

(ii) $O_1 \cap O_2 \in \tau$

(iii) $\bigcup_{\alpha \in \Lambda} O_\alpha \in \tau$

④

X i \emptyset are always in τ .

$$X = \bigcap_{\alpha \in \phi} \mathcal{O}_\alpha$$

$$\emptyset = \bigcup_{\alpha \in \phi} \mathcal{O}_\alpha$$

Given $\{a, b\}$, what are possible topologies

$$\tau_{\text{dis}} = \{\{a\}, \{b\}\} = \{\emptyset, \{a\}, \{b\}, \{a, b\}\}$$

$$\tau_{\text{ind}} = \{\emptyset, \{a, b\}\}$$

$$\tau(\text{Sierpiński Topology}) = \{\emptyset, \{a, b\}, \{a\}\}$$

$$\tau = \left\{ \left\{ [n, n+1, n+2, \dots] \right\} \right\}_{n \in \mathbb{N}}$$

is a topology

⑤

Usual topology on $\mathbb{R}, \mathbb{R}^2, \dots$

A base for $(\mathbb{R}, \mathcal{U})$ is set of open intervals $\{(a, b) : a, b \in \mathbb{R}, a < b\}$

Hausdorff's Axioms - intuitionistic version

There is an object defined for every point p in a ground space X called the neighborhood system (filter).

It is denoted by \mathcal{N}_p

① $\mathcal{N}_p \neq \emptyset \ni p \in N \in \mathcal{N}_p \quad \forall N$

② $N_1, N_2 \in \mathcal{N}_p \Rightarrow N_1 \cap N_2 \in \mathcal{N}_p$

③ Given $N \in \mathcal{N}_p \Rightarrow$ if $M \supseteq N, M \in \mathcal{N}_p$

④ Each $N \in \mathcal{N}_p$ is a superset of some $U \in \mathcal{N}_p$ where U is a nbhd of each of its own pts.

