

①

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Acceleration

$$r(t) \rightsquigarrow r'(t) = v(t)$$

$$v(t) = \frac{dr}{ds} \cdot \frac{ds}{dt} = \left( T \frac{ds}{dt} \right)$$

$$a(t) = v'(t) = \frac{d}{dt} \left( T \frac{ds}{dt} \right) = \frac{d}{dt} \left( \frac{ds}{dt} \right) T + \frac{ds}{dt} \frac{dT}{dt}$$

Chain Rule

$$= \frac{d^2 s}{dt^2} T + \frac{ds}{dt} \left( \frac{dT}{ds} \frac{ds}{dt} \right)$$

$$= \frac{d^2 s}{dt^2} T + \left( \frac{ds}{dt} \right)^2 \frac{dT}{ds} = \frac{d^2 s}{dt^2} T + \left( \frac{ds}{dt} \right)^2 (kN)$$

$$a(t) = \frac{d^2 s}{dt^2} T + k \left( \frac{ds}{dt} \right)^2 N$$

difficult

$$a(t) = a_T T + a_N N$$

$$a_N = \sqrt{|a|^2 - a_T^2}$$

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Ex 1

 $t \geq 0$ 

$$r(t) = (\cos t + t \sin t) \hat{i} + (\sin t - t \cos t) \hat{j}$$

Want to write acceleration as:

$$a(t) = a_T \mathbf{T} + a_N \mathbf{N}$$

$$\begin{aligned} v(t) &= (-\cancel{\sin t} + \cancel{\sin t} + t \cos t) \hat{i} + (\cancel{\cos t} - \cancel{\cos t} + t \sin t) \hat{j} \\ &= (t \cos t) \hat{i} + (t \sin t) \hat{j} \end{aligned}$$

$$v(t) = t \cos t \hat{i} + t \sin t \hat{j}$$

$$|v(t)| = \sqrt{t^2 \cos^2 t + t^2 \sin^2 t} = t(1) = t$$

$$a_T = \frac{d}{dt}(t) = 1$$

$$\checkmark \text{ Recall } a_N = \sqrt{|a|^2 - a_T^2}$$

$$a(t) = (\cos t - t \sin t) \hat{i} + (\sin t + t \cos t) \hat{j}$$

$$|a(t)| = \sqrt{\cos^2 t - 2t \cancel{\cos t \sin t} + t^2 \sin^2 t + \sin^2 t + 2t \cancel{\cos t \sin t} + t^2 \cos^2 t}$$

$$\dots \sin^2 t + 2t \cancel{\cos t \sin t} + t^2 \cos^2 t$$

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$$= \sqrt{\cos^2 t + \sin^2 t + t^2 (\sin^2 t + \cos^2 t)}$$

$$|\mathbf{a}(t)| = \sqrt{1 + t^2}$$

$$\therefore a_N = \sqrt{(1+t^2) - 1} = \sqrt{t^2} = t$$

So acceleration is  $a_T \mathbf{T} + a_N \mathbf{N} =$

$$= \mathbf{T} + t\mathbf{N}$$

## Practical Calculations

$$T = \frac{\mathbf{v}}{|\mathbf{v}|}$$

$$N = \frac{T'(t)}{|T'(t)|}$$

$$B = T \times N$$

$$\kappa = \frac{|\mathbf{v} \times \dot{\mathbf{v}}|}{|\mathbf{v}|^3}$$

" $\dot{\phantom{x}}$ " is time derivative

$$\tau = \frac{\begin{vmatrix} \dot{x} & \dot{y} & \dot{z} \\ \ddot{x} & \ddot{y} & \ddot{z} \\ \ddot{\ddot{x}} & \ddot{\ddot{y}} & \ddot{\ddot{z}} \end{vmatrix}}{|\mathbf{v} \times \dot{\mathbf{v}}|^2}$$

$$\mathbf{a} = \dot{\mathbf{v}} = a_T T + a_N N$$

$$a_T = \frac{d}{dt} |\mathbf{v}| \quad a_N = \kappa [s'(t)]^2 = \kappa |\mathbf{v}|^2$$

Space curve  $\mathbf{r}(t) = x(t)\hat{i} + y(t)\hat{j} + z(t)\hat{k}$

Velocity  $\mathbf{v}(t) = \mathbf{r}'(t)$  (def<sup>n</sup>)

Speed  $|\mathbf{v}(t)| = s'(t)$  (def<sup>n</sup>)

Distance along curve  $s(t) = \int_{t_0}^t |\mathbf{v}(t)| dt$  (def<sup>n</sup>)

Unit tangent  $\mathbf{T} = \frac{\mathbf{r}'(t)}{|\mathbf{r}'(t)|} = \mathbf{r}'(s)$  (def<sup>n</sup>)

Unit normal  $\mathbf{N} = \frac{\mathbf{T}'(t)}{|\mathbf{T}'(t)|} = \frac{1}{\kappa} \mathbf{T}'(s)$  (def<sup>n</sup>)

Unit binormal  $\mathbf{B} = \mathbf{T} \times \mathbf{N}$  (def<sup>n</sup>)

Curvature  $\kappa = \frac{|\mathbf{T}'(t)|}{|\mathbf{v}(t)|} = |\mathbf{T}'(s)|$  (def<sup>n</sup>)

Torsion  $\tau = -\mathbf{B}'(s) \cdot \mathbf{N}$  (def<sup>n</sup>)